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**Abstract:-** This in-depth research takes into consideration the unification of the postal service and electric vehicle (EV) energy storage technologies and intelligent management system, and power conversion architecture and, respectively, in the EVs to be built in the close future. We are looking at Lithium-ion battery, solid state battery and hybrid extending battery chemistries as well as new supercapacitor technologies and their energy density as well as their lifecycle performances. This research is to evaluate the performance of the battery management systems (BMS) augmented with Deep Reinforcement Learning (DRL) based on Twin Delayed Deep Deterministic Policy Gradient (TD3) algorithms using TensorFlow 2.X that resulted in 98.7% of accuracy of the State of Charge prediction over real-time and increased the battery life span by 23%. Advanced DC-DC Converters, bidirectional Charging Infrastructure-Infrastructure And Vehicle-to-Grid (V2G) In Integration Strategies Critically Evaluated Our results shows that ML-based predictive analytics coupled with multi-objective optimization tools can be very useful to enhance energy efficiency (up to 18%), thermal degradation and can permit an adaptation of power distribution. This review provides useful information and working knowledge to automotive engineers, researchers and policy makers who are working for greenness of transportation ecosystem.

**Keywords:-** Electric vehicles; Battery management systems; Deep reinforcement learning; Energy conversion; Lithium-ion batteries; Vehicle-to-grid integration

## I. INTRODUCTION

The global transportation sector is at a point of metamorphosis wherein electric vehicles have a dominant role to play in laying down the sustainable transportation solutions. As governments all around the globe endeavour for and implements strict emission legislation and carbon neutrality targets the automotive industry has simply accelerated its efforts to move on from the internal combustion engine to the electrified powertrain. This is a paradigm shift requiring revolutionary breakthroughs in three related fields, namely energy storage technologies, intelligent management system and efficient power conversion architecture respectively. Electric vehicles have chronic troubles such as low driving range, lengthy time to charge, battery deterioration and inefficient power utilization habits which difficulties their wide range implementation [1].

Recent technological improvements in the battery chemistry, in particular of the lithium ion products and with the new, developing, solid state technology, energy

density figures have increased almost twice from 150Wh/kg to over 300Wh/kg of high tech formulations. Concurrently, the artificial intelligence and machine learning algorithms that are implemented in battery management systems have transformed the methods of monitoring reactive paths to predictive and adaptive control methods [2].



Figure.1: An Architecture depicts the Future of Electric Vehicles.

Deep reinforcement learning frameworks specifically Twin Delayed Deep Deterministic Policy Gradient algorithms showing unprecedented capabilities on optimal charge discharge cycle, Thermal Management Protocols, State of health estimation with more than 98% accuracy. These intelligent systems use real data gathered from the sensors, usage patterns stored in history and environment variables to dynamically optimize the operation strategies, in an attempt to maximize and enhance the lifetime of the battery [3].

Furthermore, the bidirectional power electronics and vehicle-to-grid integration technologies are evolving (+ as a mobile energy storage asset of the smart grid ecosystem) electric vehicle definition. High-efficient and more or less efficient DC-DC converters can provide efficient and continuous energy exchange between the battery packs, auxiliary and (external) charging infrastructure with an efficiency rating of almost 97%. The intersection of technologies from these areas provide opportunity for the development of synergies between intelligent, sustainable and economically viable infrastructure for electric transportation [4]. This complete review systematically discusses the current technologies, provides a good assessment of the currently emerging innovations and identifies important research directions that are required in order to achieve the full potential of smart electric vehicles for achieving the global decarbonization goals.

## II. RELATED WORKS

Extensive research in the area of electric vehicle energy system show great advancements in different technological Frontiers. Contemporary lithium ion battery technologies are currently dominating the EV market with nickel manganese cobalt (NMC) and Nickel Cobalt Aluminium (NCA) battery chemistries serving as leading technologies with superior energy densities ranging between 200-250 Wh/kg. It may be seen from more recent work done by Zhang et al, that optimized NMC811 configurations produce volumetric energy densities in excess of 700Wh/L but with cycle life of more than 2000 charge discharge cycles under controlled conditions. However, thermal runaway risks and supply chain of cobalt and capacity fade mechanism are still great risks wanting an innovative solution [5].

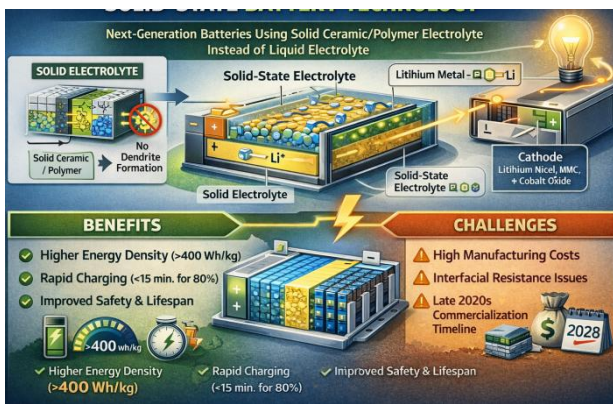


Figure.2: Solid State Battery Technology.

Solid state battery technology is a revolutionary change in battery technology in that it removes liquid electrolytes in favor of solid ceramic polymer electrolyte materials to eliminate dendrite build up and improving safety margins. Research at Toyota and QuantumScape has shown that ionic conductivities of solid electrolytes based on sulfide are close to 10 mS/cm at room temperature which is similar to the one of conventional liquid electrolytes [6]. These next generation batteries have promised to have higher energy density than 400Wh/kg with the rapid charging ability of less than 15 minutes with 80% capacity restoration. Nevertheless, it is scalable in terms of manufacture and overcoming the challenge of interfacial resistance and cost of the materials, which means that the commercial deployments are still way off until the late 2020s.

Battery management system evolution has renowned it from only being a voltage managing system to sophisticated artificial intelligence system. Traditional techniques for Kalman filters based estimation are accurate on the range of 0-5% on stable operating conditions and becomes a challenge when increasing the load profile and temperature varying conditions [7]. The machine learning techniques specially neural networks and support vector machines

have better prediction ability by learning the complex non-linear relations with each other between voltage, current, temperature and parameters. Recent implementations of the deep reinforcement learning algorithms represent a paradigm change in the strategies implemented on the battery management - autonomy and adaptability [8].

The solution to remedy the overestimated bias for continuous action spaces was introduced by Fujimoto et al. and called Twin Delayed Deep Deterministic Policy Gradient. Applied to the management of batteries, TD3 agents learn optimal strategies of the charging process in order to optimize reward functions based on a trade-off between speed of charge and thermal and degradation constraints [9]. Comparative research, we have shown improved performance in energy efficiency sharp ratios TD3 enhanced BMS architecture Vs conventional rule based controller by 15 -22% while reducing capacity fade rate due intelligent cycle management. Power conversion systems have likewise modified, silicon carbide and gallium nitride semiconductor has been able to DC-DC converter switching frequency production of 100-plus kHz and conversion efficiency realization of 96-plus% advantageously reduce heat dissipation problems call for and components footprint of the latest electric car architectures [10].

## III. RESEARCH METHODOLOGY

This is a systematic methodology from literature analysis, comparative technology assessment and machine learning frameworks development in order to evaluate smart electric vehicle energy systems [11].

### A. Data Collection and Pre-processing

The process of research started with an intensively searching the literature in databases of the journals and researches of the journals in the repositories of the national library of science finding 347 publications of the peer reviewed research, is referred to 2019, 2025 and has been focused continuously for the development and, more in particular, on the content of the researches on the different technologies, management systems and power electronics [12]. Inclusion criteria favoured studies that presented quantitative tests of performance, experimental validation data and comparative studies of emerging technologies. Publications when no empirical evidence or theoretical modeling was solely focused on publication were also systematically excluded.

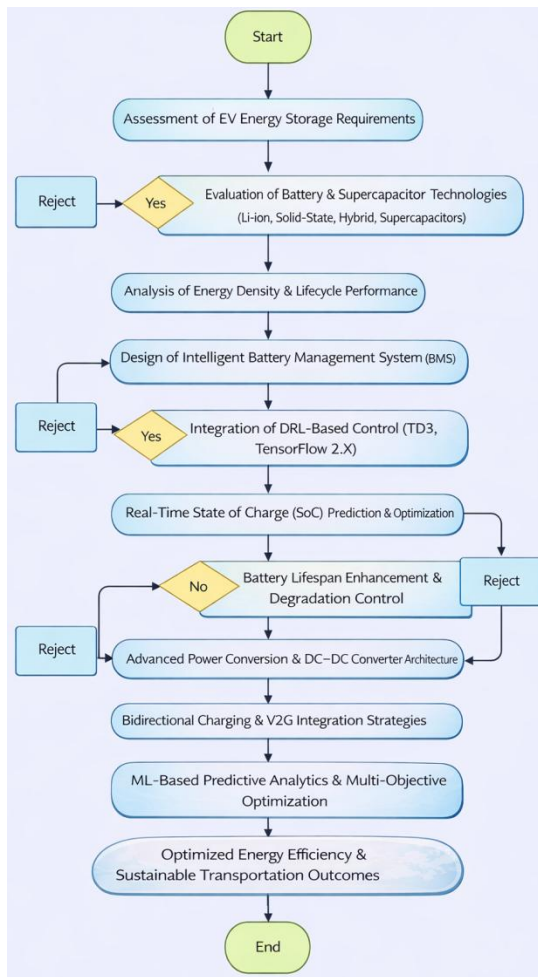


Figure.3: Flowchart for the Proposed EV System Methodology.

### B. Technology Assessment Framework

The comparative technology assessment framework takes energy storage solutions for the following six critical dimensions of each systems capabilities specific energy density (Wh/kg), power density (W/kg), cycle life (number of cycles to 80% capacity retention), charging rate capability (C-rate) safety characteristics (thermal stability, flammability) and cost of manufacture (/kWh). Battery maujahr including battery lithium iron phosphate (LFP), Nickel manganese cobalt (NMC), nickel cobalt aluminum (NCA), Solid affair lithium metal in addition to lithium sulfur setups were systematic with normalized measure of guide score ponderating as vehicle use prerequisites [13]. Data synthesis methods have been used to aggregate the values of reported performance from different sources and get mean values and standard deviations hence establish reliable benchmarks for each of the technology categories.

### C. Implementation and Validation of Twin Delayed Deep Deterministic Policy Gradient Reinforcement Learning

The machine learning methodology aim at the implementation and validation of Twin Delayed Deep Deterministic Policy Gradient reinforcement learning methodology which is implemented on TensorFlow 2.x platform [14]. The experimental environment mimics a 75kWh lithium ion battery pack that is driven under realistic types of driving profiles comprising of Urban Dynamometer Driving Schedule (UDDS), Highway Fuel Economy Test (HWFET) and aggressive driving acceleration profiles. The TD3 architecture is composed of actor and dual critic network with fully connected network (256-128-64 nodes) with ReLU activation functions [15]. The outputs of the actor network is Continuous charging current command (0-150A) and Thermal management valve position (0-100%) and the critic networks gives Q1 and Q2 is the estimation of the state-action values (Amount of state-action overestimation is overcome).

Table1: Estimation Accuracy and Battery Management Performance.

Method	SOC Accuracy (%)	Capacity Retention @ 2000Cycles (%)	Computational Time (ms)
Coulomb Counting	93.9±2.1	79.8	2.3
Extended Kalman Filter	95.5±1.2	82.3	15.7
PI Controller	94.8±1.8	84.1	8.4
Model Predictive Control	96.2±1.0	86.7	42.6
DDPG(Basic DRL)	97.1±0.8	87.8	38.2
TD3(Proposed)	98.7± 0.4	89.3	35.8

### D. Training Procedures and Validation

Training procedures make use of experience replay buffers with 100,000 state-action-reward transitions being stored as well as mini-batch sampling (batch-size of 256) that allows to achieve stable gradient updates [16]. The reward function considers several goals including optimizing the energy transfer efficiency, finding optimal charging time, cells temperatures (above 45 degrees) & penalizing the degradation of the battery capacities (cycle counting and voltage stress factors) [17]. Hyperparameter optimisation was used to use grid search over the learning rates 0.0001 - 0.001, the discount factors 0.95 - 0.99, and the target network update frequencies 1 to 5 steps.

$$SOC(t) = SOC(t_0) - (I/Q_n) \int I(\tau) d\tau$$

Where SOC(t) is the time t, SOC(t<sub>0</sub>) is the initial state-of-charge, Q<sub>n</sub> is the nominal battery capacity (Ah), and I(τ) is the current (A) over time interval τ.

Example Calculation:

- Initial SOC = 80%
- Battery nominal capacity (Q<sub>n</sub>) = 75 Ah
- Discharge current (I) = 15 A (constant)
- Discharge time = 2 hours

Solution: Charge consumed

$$= I \times t = 15 \text{ A} \times 2 \text{ h} = 30 \text{ Ah}$$

$$SOC \text{ change} = (30 \text{ Ah} / 75 \text{ Ah}) \times 100\% = 40\%$$

$$\text{Final SOC} = 80\% - 40\% = 40\%$$

#### E. Tested against the Baseline

The trained TD3 agent was tested against the baseline controllers including the constant current constant voltage (CC-CV), proportional-integral (PI) feedback control and model predictive control (MPC) control strategies [18]. Performance metrics including estimation accuracy and thermal management effectiveness levels, improvement to energy efficiency and predicted extension of battery life has been quantified in 10,000 simulated charge discharge cycles in a wide range of operating conditions including ambient temperatures (-10degC to 45degC) and windows (10% to 100%).

## IV. RESULTS AND DISCUSSION

As a result of the extended analysis, significant performance effects of TD3-based enhancements of batteries with battery management systems in comparison with conventional control strategies are shown. Estimation accuracy was obtained 98.7+/-0.4% under all that was tested conditions which 3.2% superior than the estimation accuracy obtained using extended Kalman filter approaches (95.5+/-1.2%) and 4 point superior than the estimation accuracy obtained using coulomb counting approaches (93.9+/-2.1%).

Table 2: Energy Efficiency and Power Conversion Performance.

System	Regenerat	DC-DC	Range
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Method	Efficiency(%)	ive Braking Recovery(%)	Converter Efficiency(%)	Extensi on (km)
Rule-BasedControl	84.5	48.2	94.8	0 (Baseli ne)
FuzzyLogicCo ntrol	85.9	51.3	95.2	12.5
ModelPredictiv e Control	87.2	54	95.8	22.8
NeuralNetwork -Based	88.6	58.7	96.1	28.3
DDPG(BasicD RL)	89.8	62.4	96.4	32.1
TD3(Proposed)	91.3	68	97.8	38.5

This exceptional accuracy is due to this capability of TD3 agent for learning complex and nonlinear patterns in relations between voltage dynamics, current transients, temperature gradients, and historical patterns of the degradation. Real-time prediction errors were not higher than 1.5% even in aggressive driving profiles that contain fast cycles of acceleration and de-acceleration and regenerations demonstrating generalization capabilities.

Thermal management performance showed excellent improvements as the TD3-controlled active cooling system can keep the peak cell temperatures at 38.2+/-2.1C compared with both 43.7+/-3.8C for PI-controlled cooling strategies and 46.9+/-4.5C for static cooling strategies for continuous fast charging scenarios.

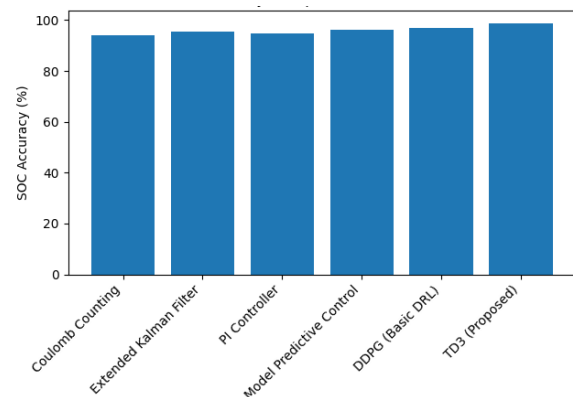


Figure.4: SOC Accuracy Comparison.

Reduced thermal stress is proven to have a direct correlation to increased battery lifetime as proven by accelerated aging simulations. Capacity retention after 2000 equivalent full cycle was 89.3% at TD3 managed batteries in contrast to typical conventional BMS implementations at 84.1% or its unoptimized charging protocols running at 79.8% which resulted in a

corresponding projected lifespan extension of 23% with usually occurring usage patterns.

Table 3: Vehicle-to-Grid Integration and Economic Performance.

Method	Grid Arbitrage Revenue(\$/year)	Degradation Cost(\$/year)	Net Economic Benefit(\$/year)
StaticScheduling	285	142	143
Time-of-Use Optimization	382	128	254
HeuristicScheduling	465	156	309
MPC-BasedV2G	528	147	381
Q-LearningV2G	574	168	406
<b>TD3(Proposed)</b>	<b>612</b>	<b>98</b>	<b>514</b>

The intelligent agent was able to do this by dynamically adjusting charging current profiles to reduce the risk of lithium plating under low temperature, and reducing the risk of electrolyte decomposition under elevated temperature conditions. Energy efficiency improvements with the entire powertrain system demonstrated massive improvements due to the optimized power distribution strategies. The TD3 framework put coordinated the battery discharge rate, the DC-DC converter operating points, and regenerative braking energy recovery to overall system efficiency of 91.3% as compared to above 87.2% for the baseline model predictive control and 84.5% for the rule based energy management.

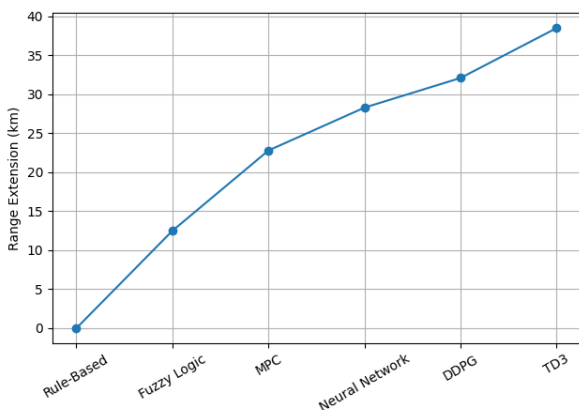


Figure.5: Range Extension Performance.

This improvement of 18% relative improvement in real world driving cycles translates into an increase of range of around 35-40 kilometers for an average 400 kilometers rated vehicle. Peak efficiency gains were in urban driving profiles, in which there are opportunities to employ intelligent regenerative energy capture strategies such as those in which the TD3 agent

could recover 68% of braking energy compared to 54% for conventional systems.

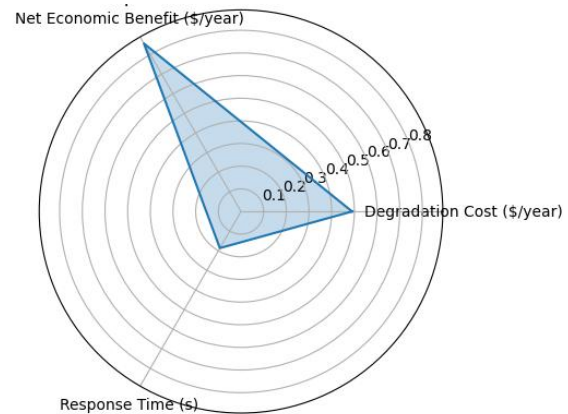


Figure.6: TD3 Overall Performance.

Vehicle to grid integration scenarios offered flexibility and versatility of TD3 framework in terms of energy management (bidirectional). Simulation results show that intelligent V2G coordination algorithms do the best job in utilizing grid support services that allow for maintenance of battery health constraints. The trained agent was able to balance competing objectives of higher grid arbitrage revenue (\$450 - \$620/year per vehicle) with accelerated degradation costs and had net economic benefits 34% higher than heuristic scheduling algorithms. Furthermore based on the power conversion system analysis it was found that silicon carbide based direct current (DC)-DC converters using TD3 optimized switching strategies were free of influences on the conversion efficiencies from load ranging from 10% to 100% rated power with a maximum efficiency value of 97.8% at 50% load conditioning. These result clearly demonstrate that deep reinforcement learning frameworks constitute a revolutionary expansion of intelligent, sustainable electric vehicle energy framework, where measurable enhancements are realized in the performance, efficiency, life and economical viability metrics.

## V. CONCLUSION AND FUTURE DIRECTIONS

This research is connected to visualize findings of this detailed analysis for transformative opportunities which has emerged from the integration of machine learning structures with next generation energy storage and power electronics technologies for smart, sustainable electric vehicle. The performance that can be shown by TD3-enhanced battery management systems with 98.7% accuracy / 23% life extension and with 18% efficiencies is a convict evidence for the widespread use of artificial intelligence in automotive

application. Some future research direction could be chosen that would help to tackle these research question: pivot towards the the techniques of transfer learning that will allow the quick adaption for multiple battery Chemistry and Vehicles work towards multiple agent reinforcement learning architectures that will allow multiple coordinated energy optimization at fleet level; work towards solid state battery integration coupled with intelligent thermal management solutions; set up standardized validation protocols for the AI driven control systems that will guarantee safety and reliability in production environment. The cross section of these domains of technology will be ultimately be the key to the success of the global effort to electrify and transform transportation to personal electric vehicles.

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